



# Project F.I.R.E: Fire Intelligent Response Equipment

Group 4

Noora Dawood • Nicholas Hainline • Jonathan Kessler • Arisa Kitagishi

- **Senior Design 2: Critical Design Review**

.

# Meet the Engineers:



**Jonathan Kessluk**  
Computer Engineering

**Focus:**

- Wireless Communication
- Software Design
- PCB Design



**Arisa Kitagishi**  
Computer Engineering

**Focus:**

- Machine Learning
- Computer Vision
- Programming



**Nicholas Hainline**  
Electrical Engineering

**Focus:**

- Power System Design
- Device Enclosure
- PCB Design



**Noora Dawood**  
Electrical Engineering

**Focus:**

- Sensor Technology & Data Collection
- PCB Design
- Sponsor Liaison

# Goals, Objectives, Specifications, and Requirements

## Objective:

To design a system to alert authorities to the potential of a fire (or forest fire)

## Goal:

The system is small, lightweight, low power, and self sufficient

## Requirements

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- The system shall detect the presence of a fire within 100m
- The system shall communicate wirelessly to nearby nodes
- The system shall be able to withstand normal weather conditions
- The system shall charge a battery with solar panel
- The system battery shall last 36 hours without charging

## Specifications

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- The system reads Temperature, Gas, and IR sensors periodically and store data internally
- The system processes all sensor data and images to determine if a fire has started
- The system uses LoRa for wireless communication
- The system contains a network controller and a sensor controller

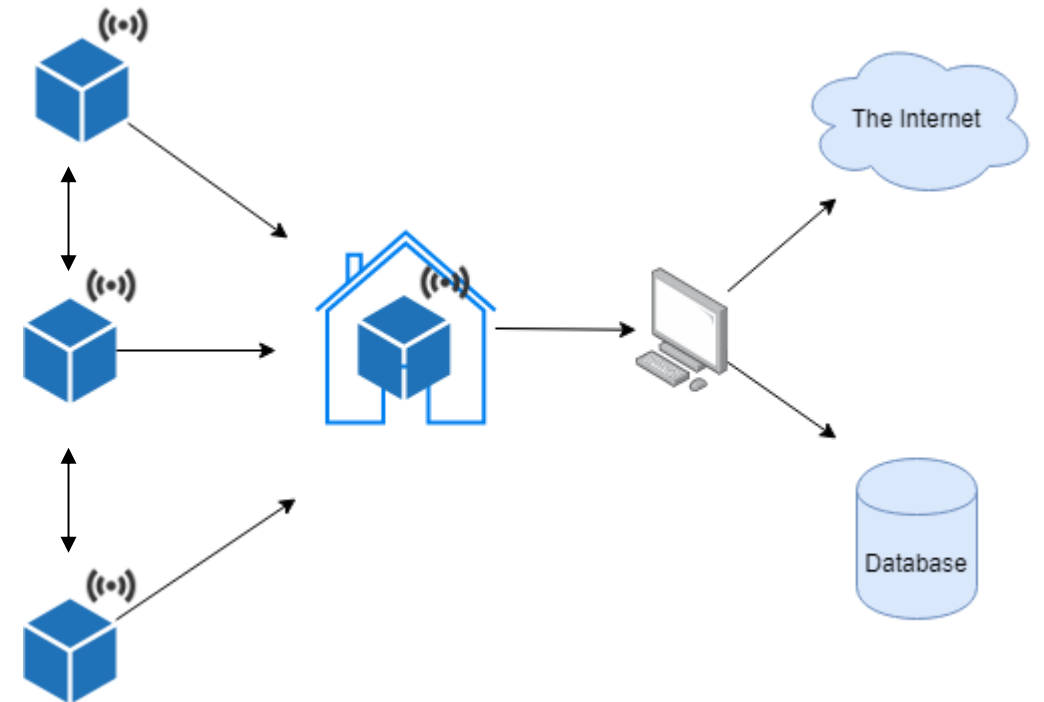
# Detecting a Fire

- Standalone sensors
- Camera + Human Interaction
- Camera + Machine Learning
  
- Solution: All of them!
  - Machine Learning to decide if a fire is likely.
  - Sensors to add confidence to the decision.
  - With low confidence, a human can be alerted to decide.

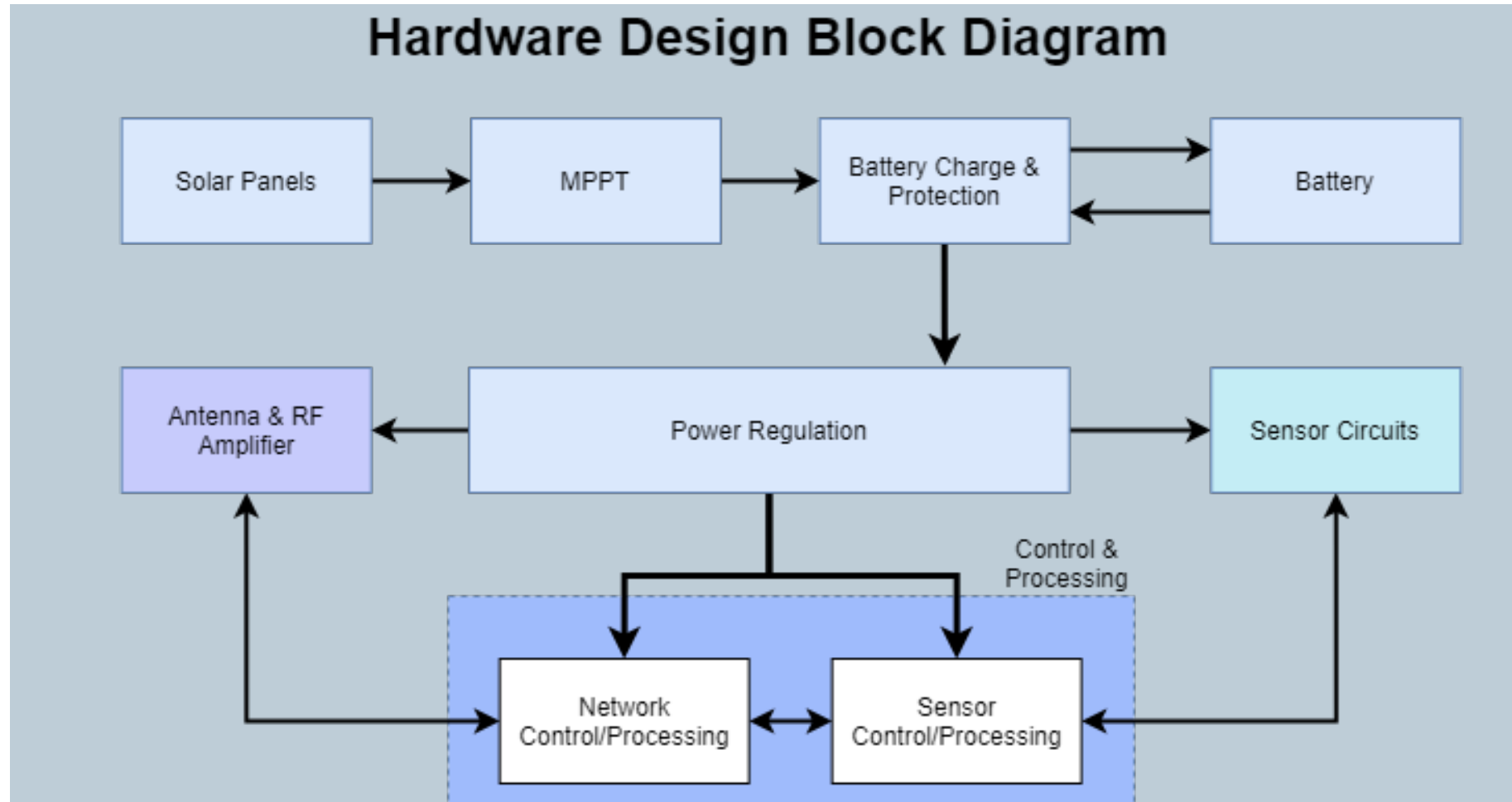


# The Entire System

- Multiple Nodes that can sense fire within their local area
- Each node can send data to other nodes
- Endpoint acquires data and determines what to do with that data
- Every node must communicate with the Endpoint



# Block Diagram of a Single Node



# Wireless Communication

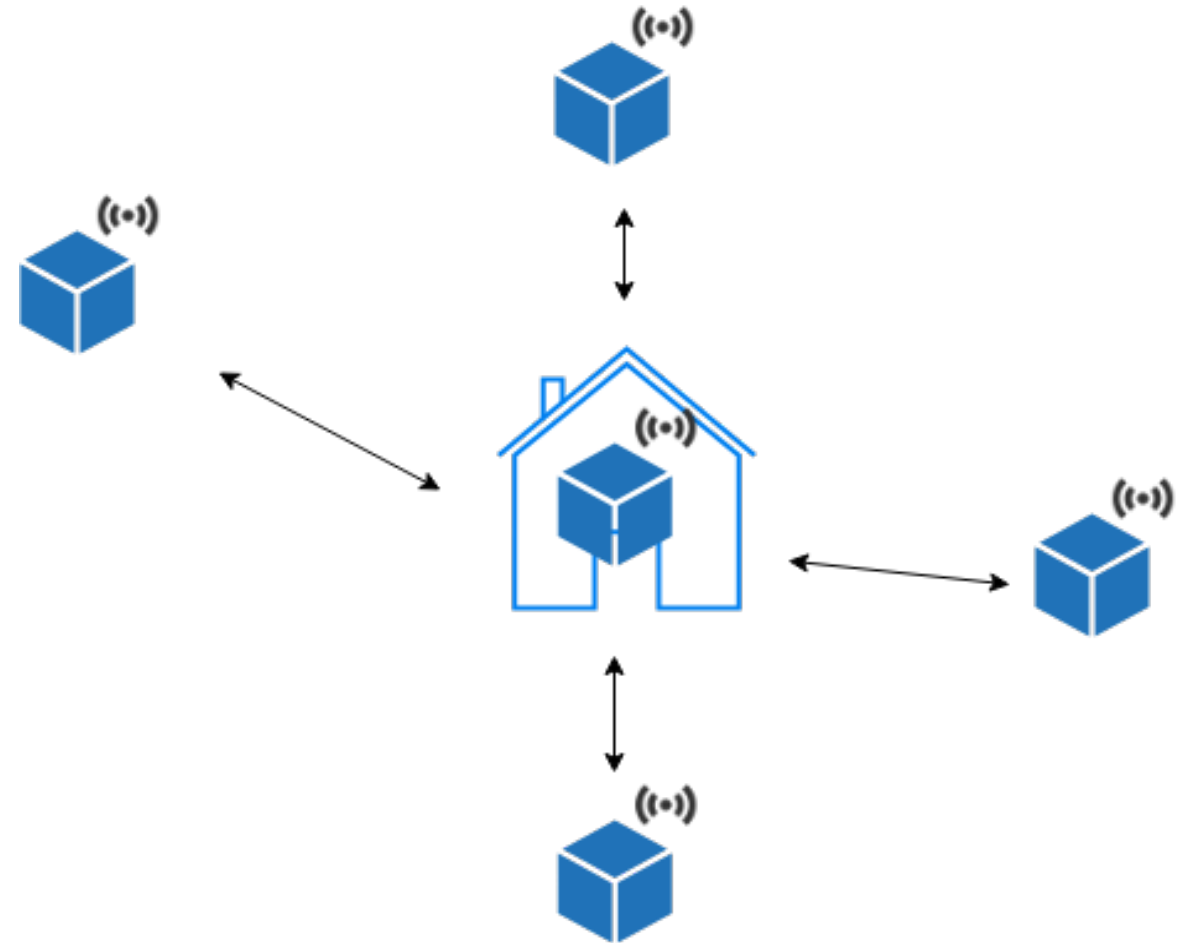
**Jonathan  
Kessler**  
Computer  
Engineering



# Mesh VS Star Topologies

## Star Topology

- Complexity is localized at a central node.
- Nodes can sleep after transmission.
- Loss of central node results in the entire system disconnecting.

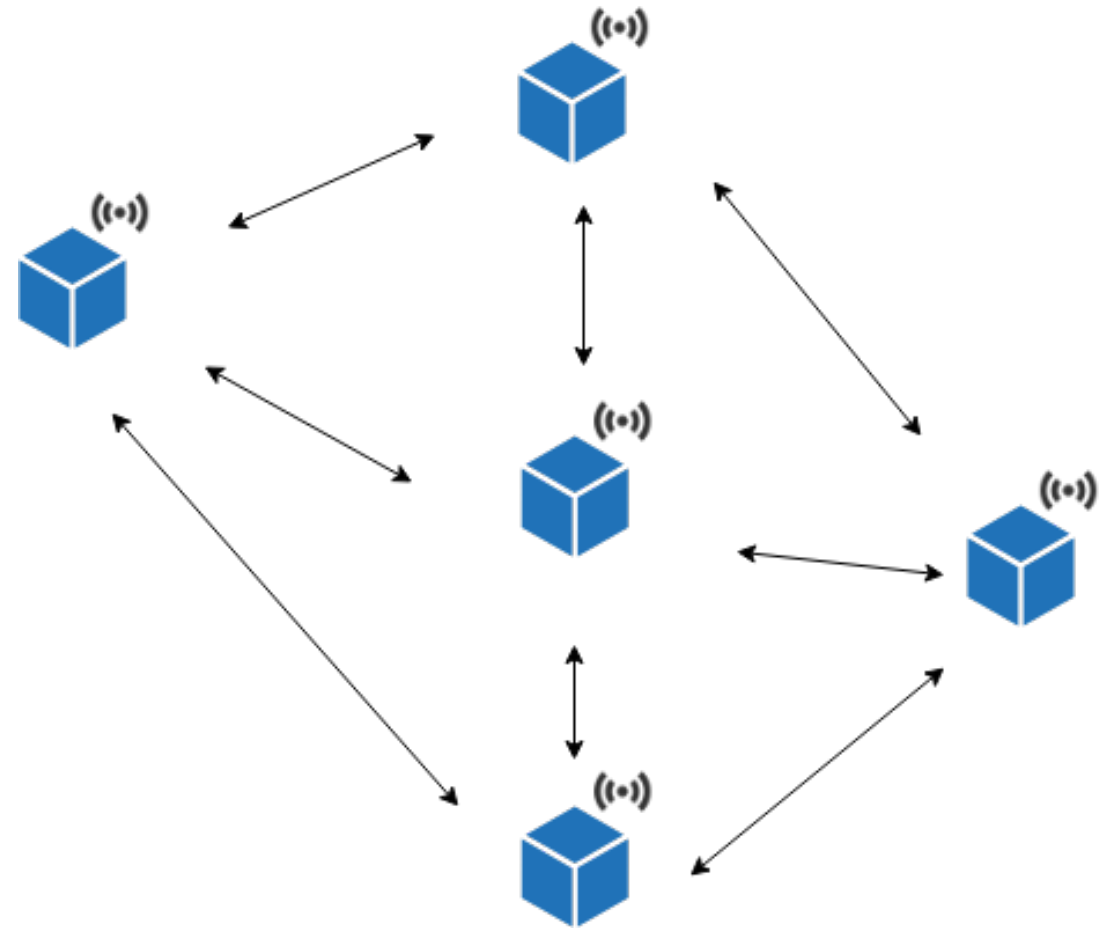




# Mesh VS Star Topologies

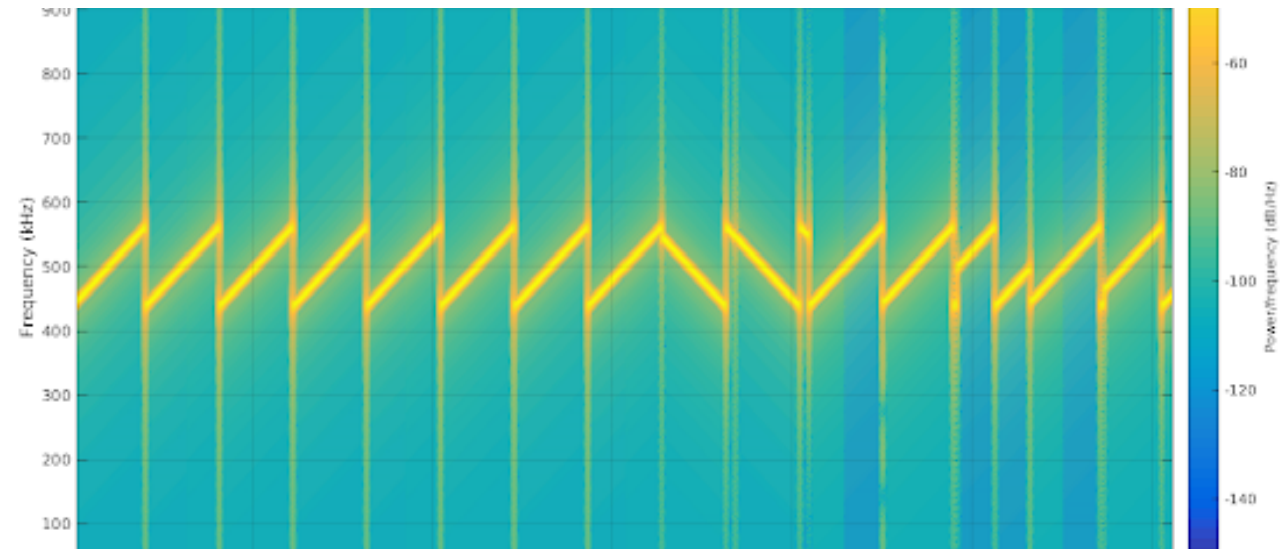
## Mesh Topology

- All nodes cooperate to distribute data
- Loss of node is acceptable: all other nodes can still communicate (assuming no bottlenecks)
- Nodes must actively listen for transmissions at all times



# LoRa: Long Range

- Uses a derivative of Chirp Spread Spectrum Modulation (CSS)
- Can use the 400MHz and 900MHz bands
- Link budget of 155-170dB
- In ideal conditions, can reach >10km



# Controllers

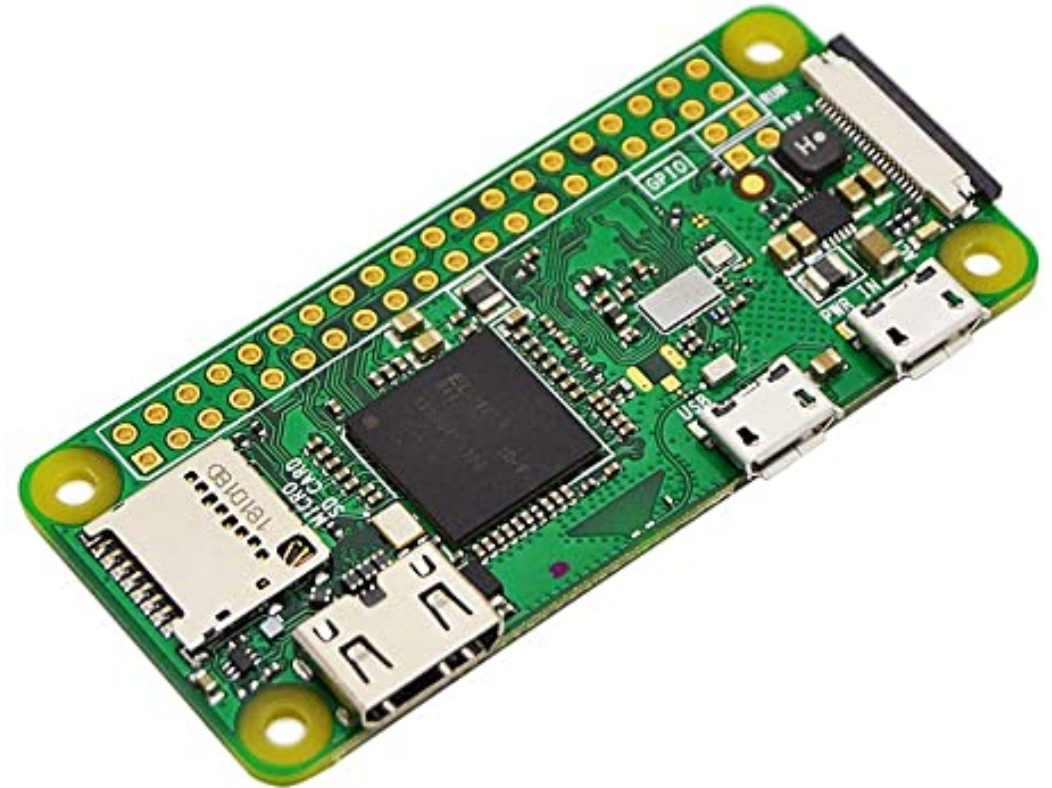
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Computer  
Engineering



# Processing Subsystem

## Raspberry Pi

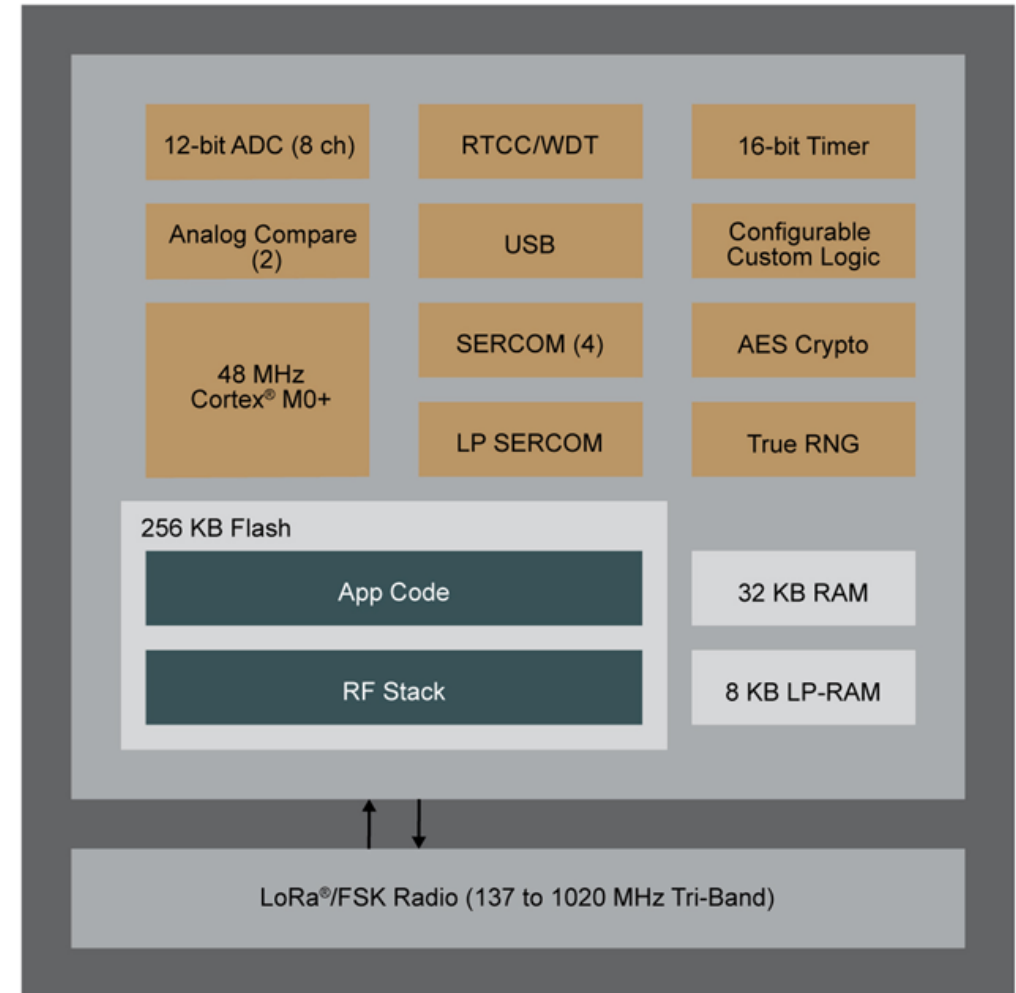
- Easy to program with Linux OS
  - Python, C, C++, Bash, many packages
- Provides many communication interfaces
  - I2C, SPI, UART, 26 GPIO, USB
- Many resources available
- Higher than desired power usage



# Network Subsystem

## SAMR34/5

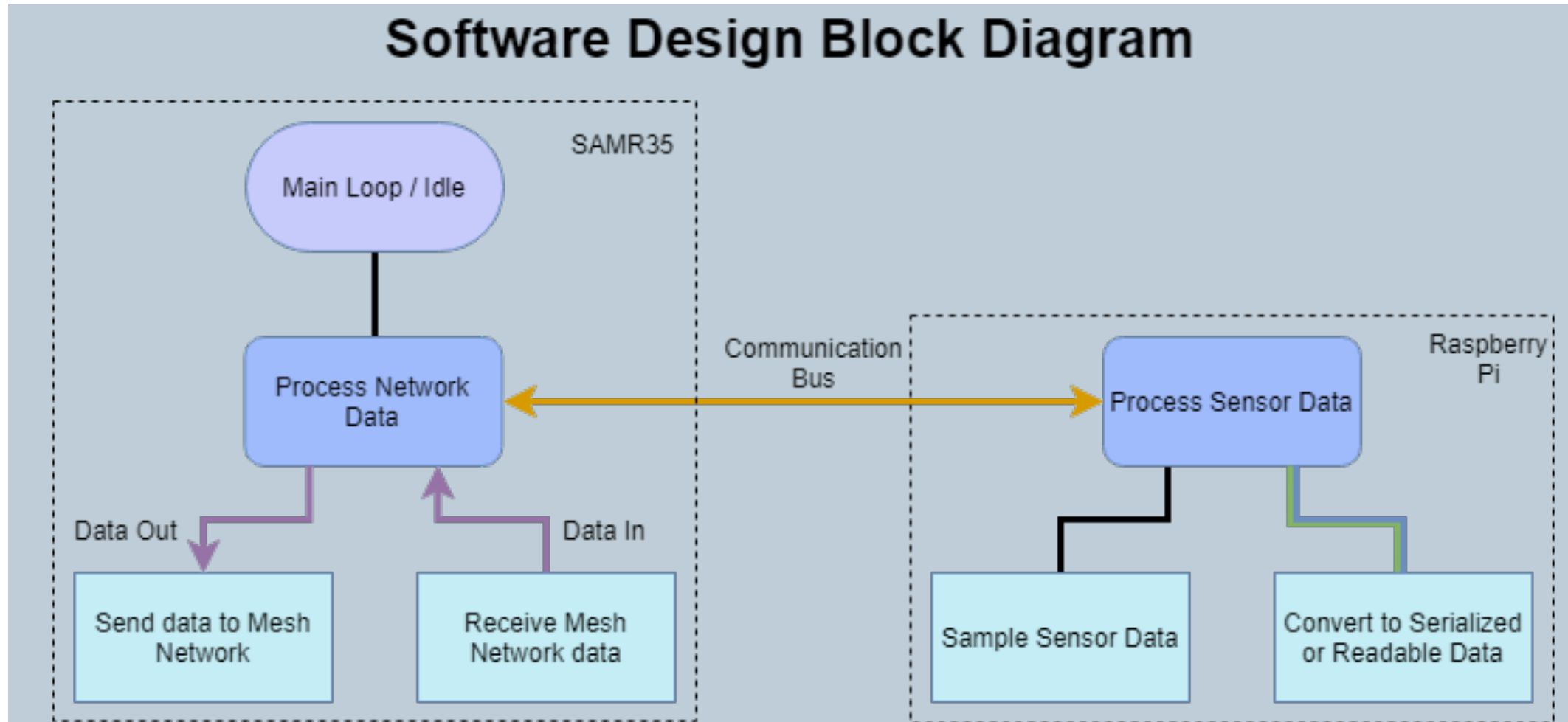
- C or C++ embedded system
- Internal 32-bit Arm Cortex M0+
- Up to 256KB Flash and 40KB RAM
- Sleep current is 790nA
- Built in LoRa UHF transceiver communication interface



# Software Design

**Jonathan  
Kessler**  
Computer  
Engineering



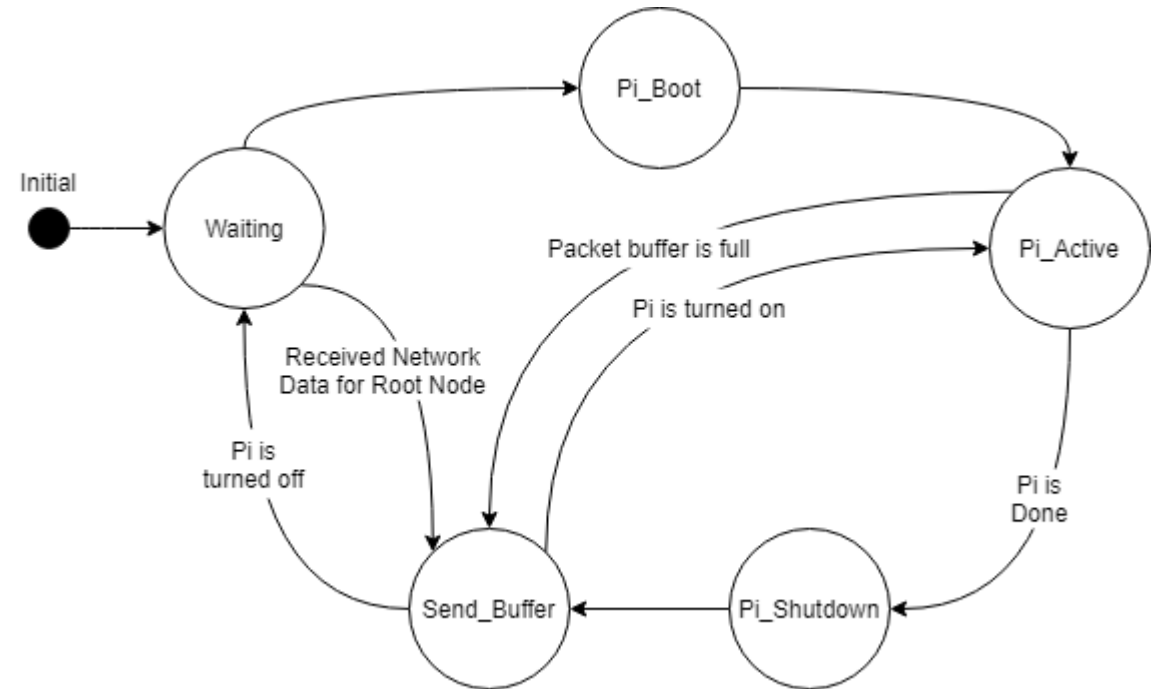


# Simplified State Diagram

Order of operations:

1. Wait for timer to finish
2. Boot Raspberry Pi
3. Get data from Raspberry Pi & Transmit the data
4. Shutdown the Raspberry Pi
5. Wait

If there is a received packet when waiting/idle, forward that packet to the network



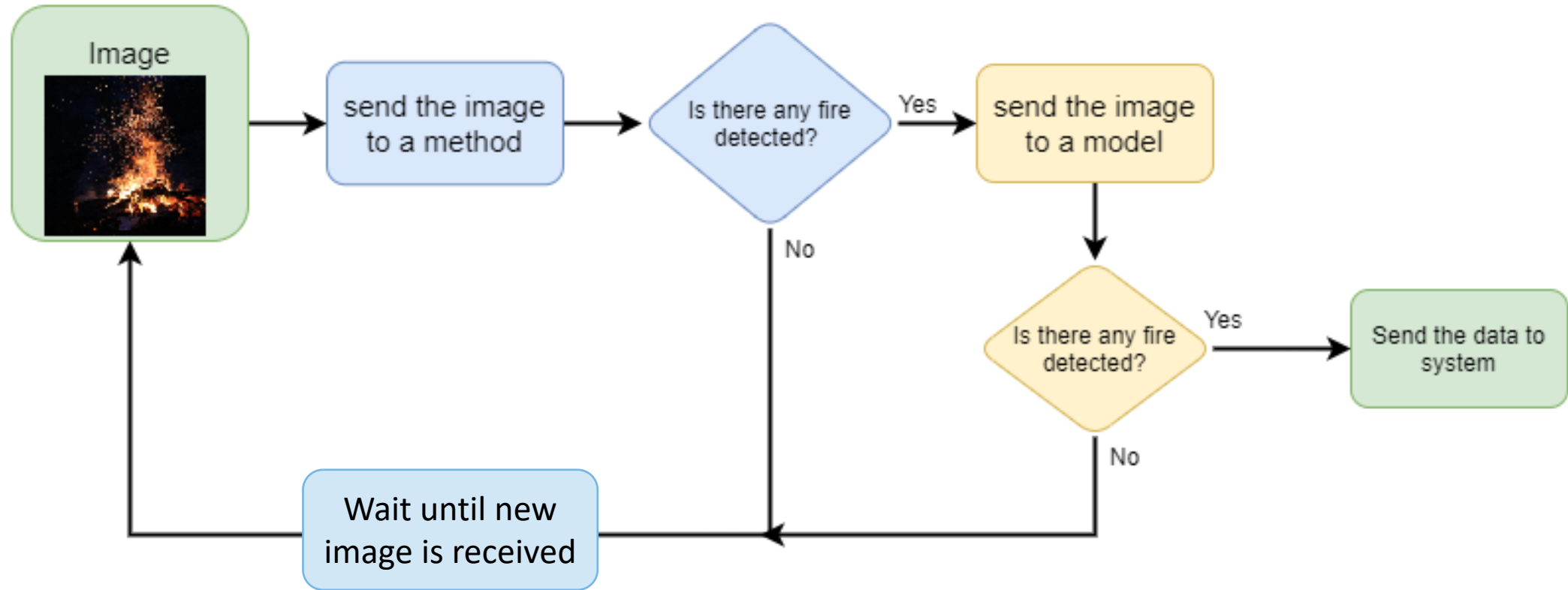


# Computer Vision

**Arisa  
Kitagishi**  
Computer  
Engineering



# Design/ Objective

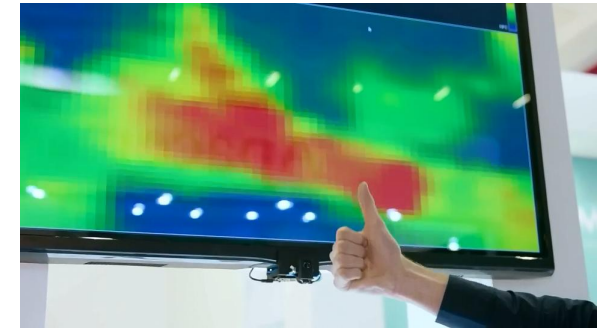


# Significant Component Decisions

**SIEMENS**  
*Ingenuity for life*

Which camera to use?

- **Thermal Camera:** MLX90640 thermal camera by Melexis Technologies
  - Price: ~\$60
- **PiCamera:** LoveRPI 5MP Camera Module
  - Price: ~\$10



# Successes: Color Classification



Frame 1



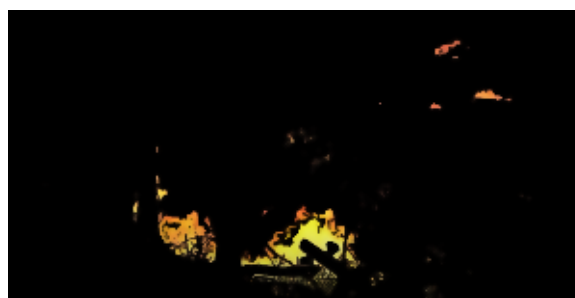
Mask



Contour



Frame 2



Mask



Contour

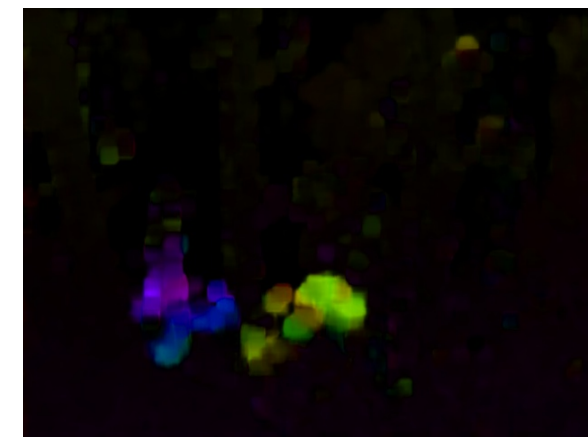
# Successes: Optical Flow



Frame 1



Frame 2



Optical Flow

# Difficulties: Color Classification

(1)



Higher value of  
epsilon

(2)



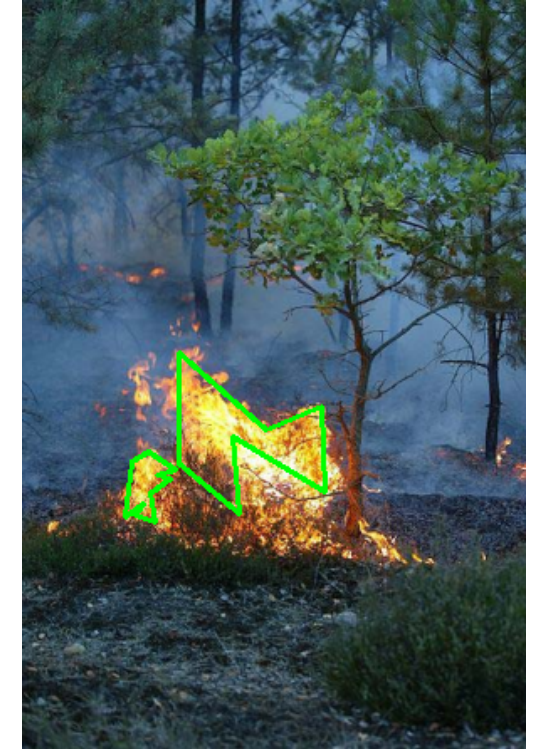
Lower value of  
epsilon

(3)



Different Filter

(4)



Lower Threshold  
of Area size

# Difficulties: Color Classification

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## Difficulties: Machine Learning

- Limited RAM, slower processor
- Unfamiliarity
- Limited Dataset
- Difficult acquiring the picture from desirable environment
- Time Consuming:
  - training, adjusting hyperparameters, obtaining appropriate pre-trained model

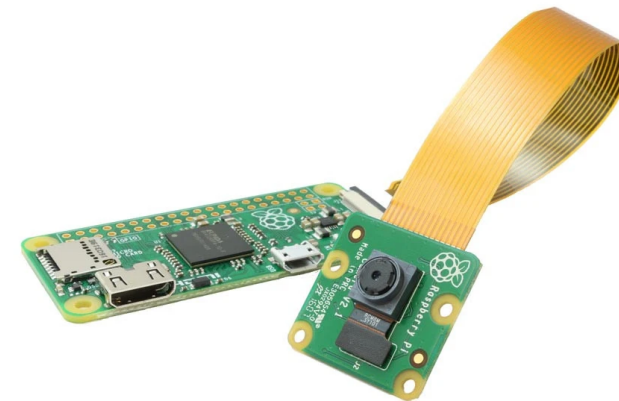
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TensorFlow



python





# Power System & Enclosure

**Nicholas  
Hainline**  
Electrical  
Engineering

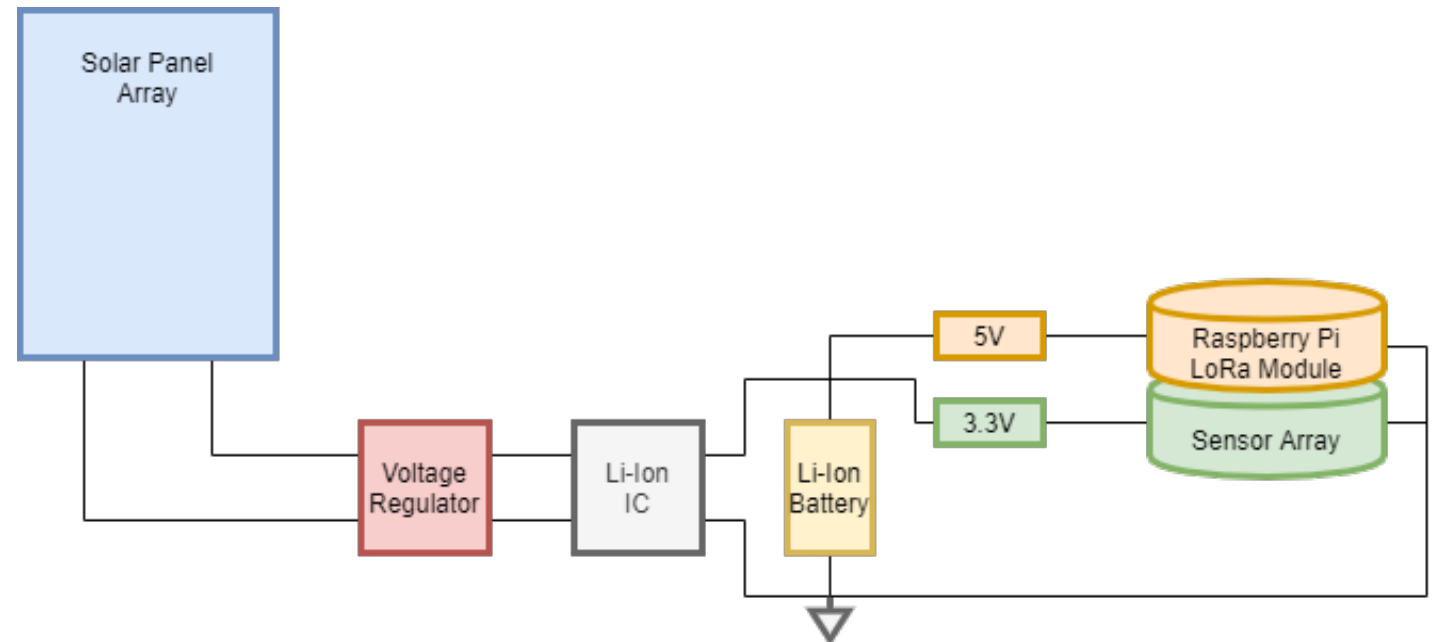


# Power System Design

## Requirements:

- Power Storage
- Charging system
- Two power rails, one 5-volt and one 3.3-volt rail

If possible, under perfect solar conditions have the system run completely off solar and the battery would be a backup.



## Choosing The Right Battery

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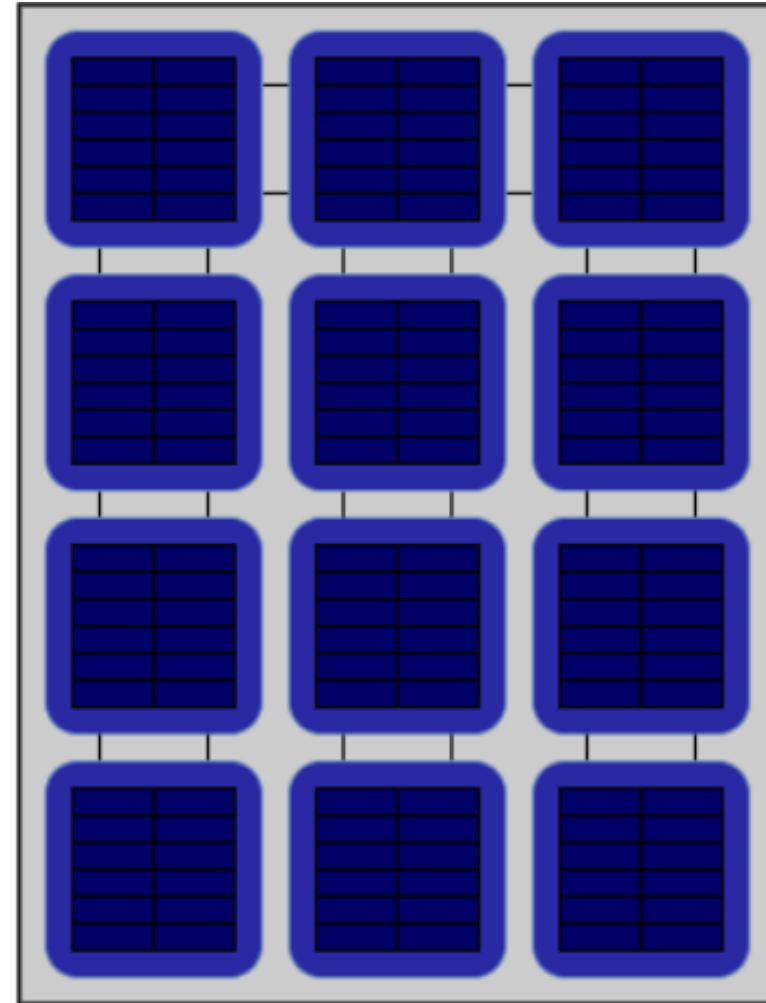
- 18650 Lithium Ion Cells were chosen for the power storage.
- Will include battery protection IC on them and will be charged with a li-ion IC.
- Battery protection is a major point as Li-ion cells are volatile if mishandled
- Provide the best discharge curve and size to storage ratio.



## Integration of Solar Array

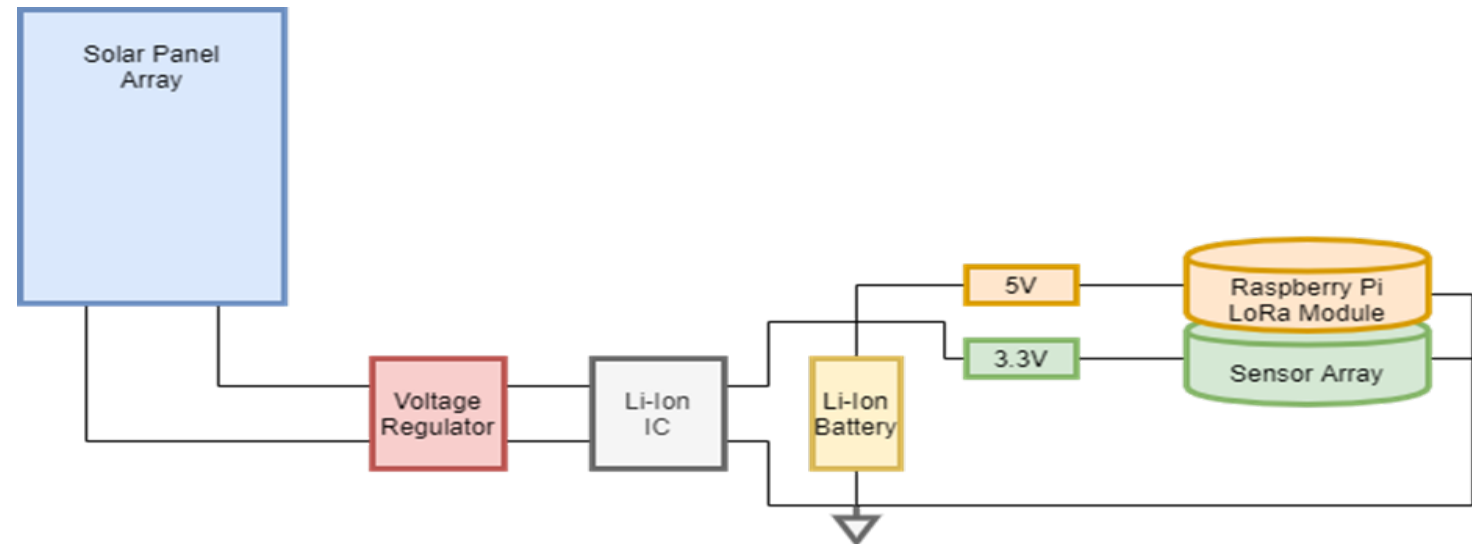
The goal is to have it keep the batteries charged during the day.

- Nighttime will use the batteries
- Daytime will use the solar panel as much as possible.
- This set up minimizes the load on the batteries extending the life cycle of them.



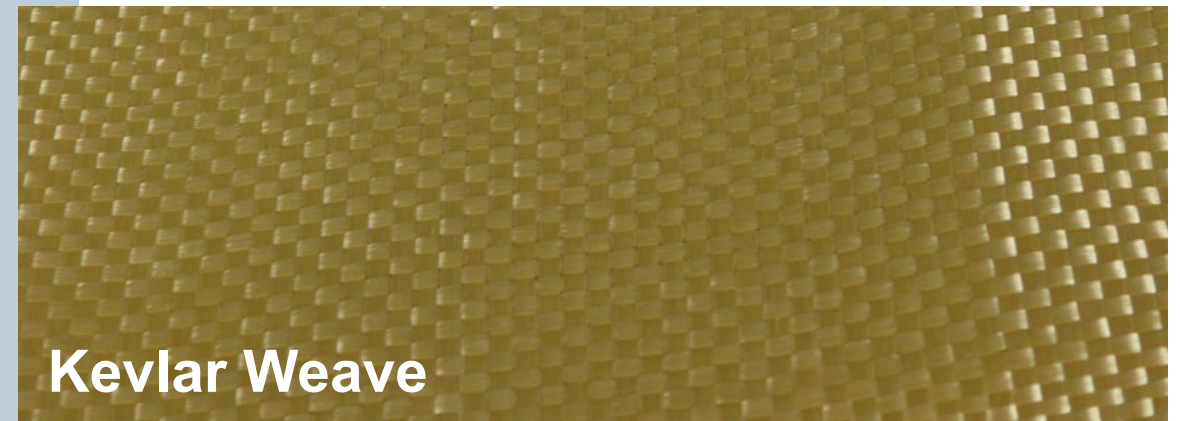
# Power System Implementation

1. **Voltage Regulator:** output a constant 5 volts.
2. **Li-ion IC:** takes this and charges the battery or bypasses it to run the system.
3. **Two Buck-Boost converters:** output 5 volts and 3.3-volts to run the Raspberry Pi and the sensor array.



# Fire Resistant Enclosure

- For the enclosure for the system it will need to be able to deal with intense heat and two easy to handle materials exist to deal with fires.
- Kevlar and carbon fiber are both fire retardant and make very strong composite materials.
- For the prototype phase of this project the encloser will be 3D printed.



# Sensors

**Noora  
Dawood**  
Electrical  
Engineering



### Flame:

- Detect pulsation of flames: flicker
- Detect image of fire using a camera

### Smoke:

- Detect presence of smoke in a smoke chamber

### Gas:

- Detect gas particles in the atmosphere



# Fire Detection Sensors



## Voltage Supply:

Between 3.3V to 5V



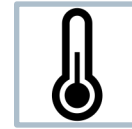
## Signal protocol:

I2C



## Component Packages:

SOIC, WSOIC, mSOIC, SOJ, SOP, SSOP, TSOP, TSSOP, SOT, TO, THT, DO, SIP or SIL



## Operating temperature



## Cost:

\$10 - \$30



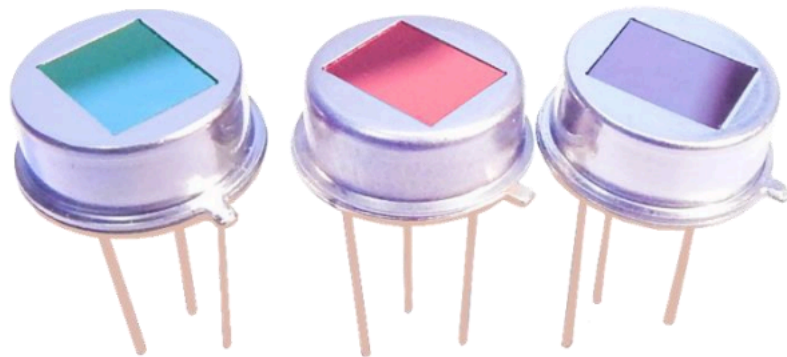
## Average Current

Average active current of the system: 100mA  
Sensors should use lowest possible current

## Potential Flame Sensors:

### Pyreos PY0573

- 2.7 – 8V input
- TO-39
- 1 (only) for \$56.92
- Analog signal
- Flame flicker 8-10 Hz
- 1 for \$56.92



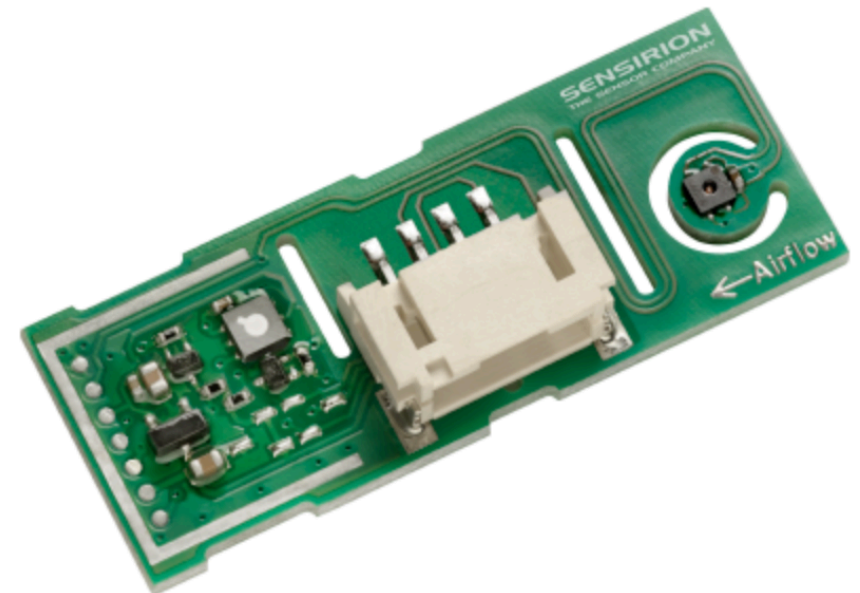
### Pyreos EPY12241

- 1.75 - 3.6 V input
- SMD/BO board option with header pins
- \$34.13/\$41.54
- I2C signal
- Flame flicker 3-30 Hz
- 1 for \$34.13/\$41.54



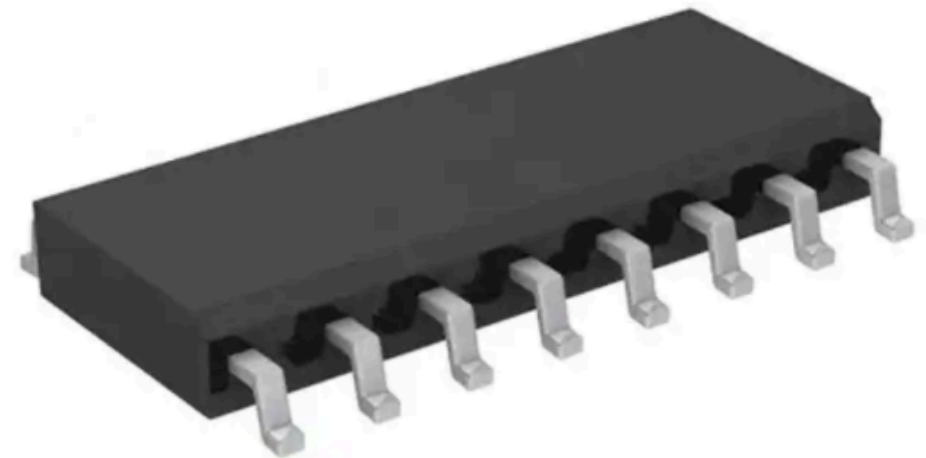
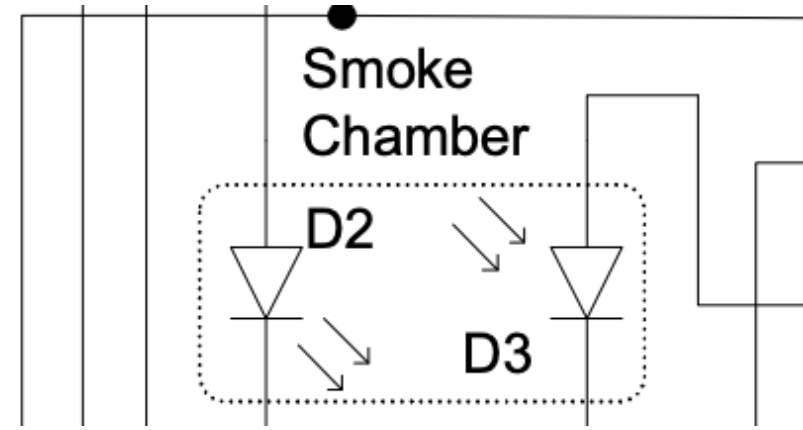
# Gas Sensor

- Sensirion SVM30
- Output:
  - Total VOC (60,000 ppb)
  - H<sub>2</sub>-based CO<sub>2</sub>eq (60,000 ppm)
  - Relative humidity
  - Temperature
- Input: 4.5 - 5.5 V
- I<sup>2</sup>C signal
- SMD, mounted with screw and connector
- 1 for \$24.26



# Smoke Sensor

- Microchip Technology RE46C190S16TF
- CMOS Low Voltage Photoelectric Smoke Detector
- SOIC package → SOIC to DIP adapter
- Smoke chamber (comparator)
- Voltage output
- 2 – 5V input
- 1 for \$1.30



# Administrative

**Noora  
Dawood**  
Electrical  
Engineering



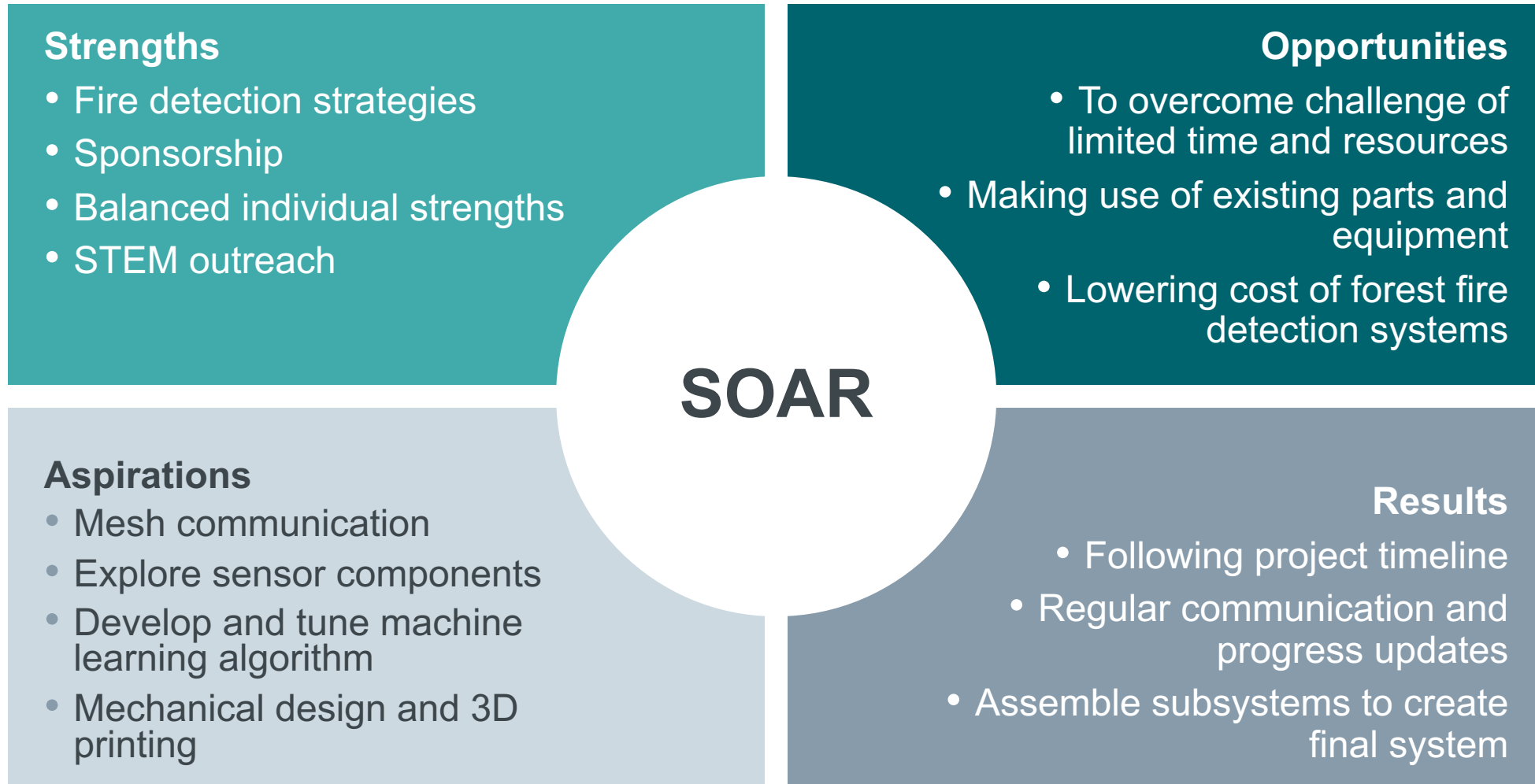
# Project Budget



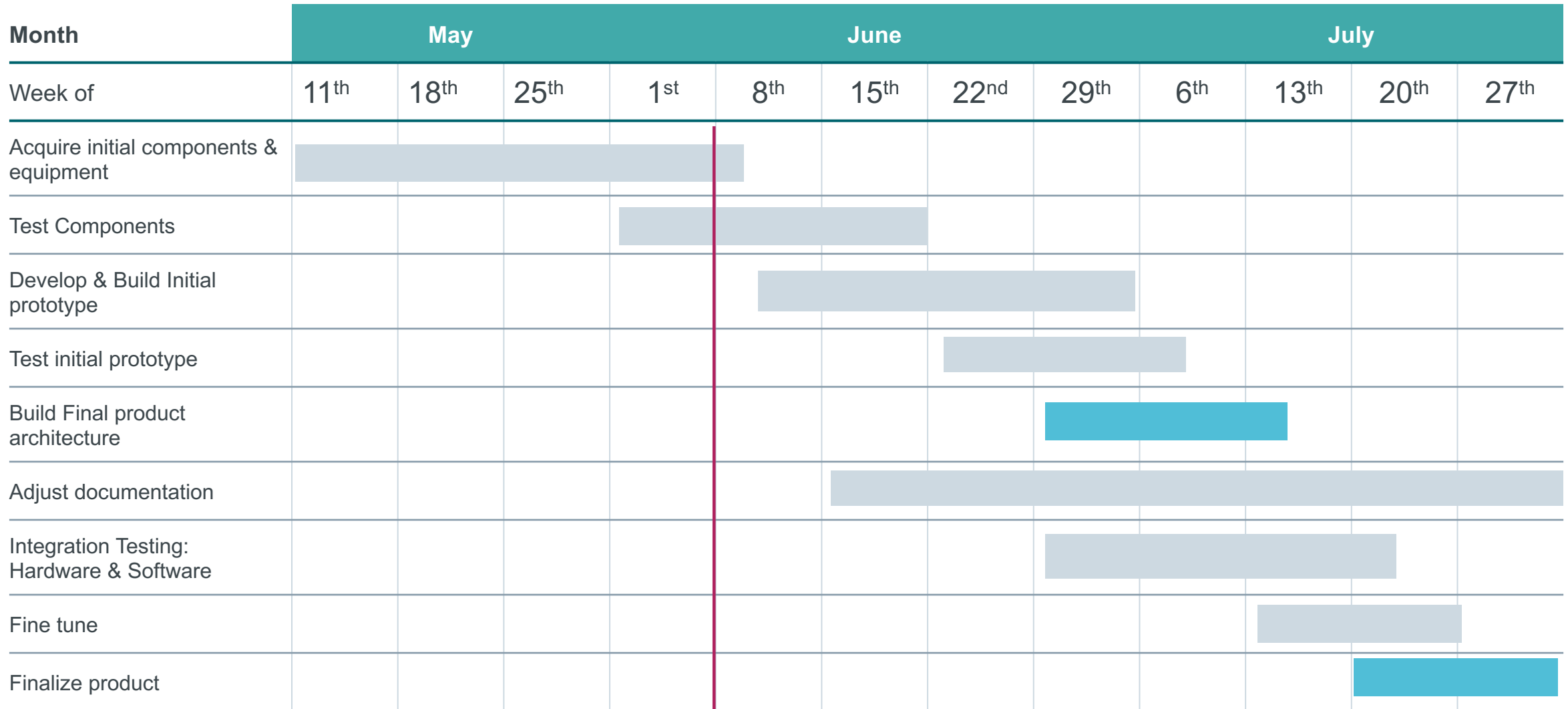
- **Sponsor: Siemens STEM Initiative**
  - Allocated \$500 budget
  - Educational EE kit for future STEM events
  - Project's connection to SIEMENS industry:
    - Gas Turbine Fire and Gas sensor system
    - Wind Turbine fire detection and extinguishing system
    - Digitalization/Internet of Things

Item	Estimated Cost (\$)
<b>Solar Panel System</b>	100
<b>Sensors*</b>	
Gas sensors	50
Infrared sensors (flame detection)	50
Particle sensors (smoke detection)	20
Thermal Camera / Sensor Array	200
Temperature	1
Humidity	1
<b>Electronics*^</b>	
Controller	20
General components (resistor, capacitors, inductors, connectors) ^	30
Specialized components (voltage regulation, MPPT, radio frequency) ^	30
<b>PCB Manufacturing*^</b>	60
<b>Prototype (machine shop labor if applicable)</b>	80
<b>Development kit (for software)^</b>	30
<b>Miscellaneous (solder and jumper wires)</b>	40
<b>Total Cost**</b>	≈ \$500.00***

# SOAR Analysis



# Project timeline



05.06.2020



# Success Checklist

1	Finish network and software tests and interpret results	✓
2	Perform long term battery testing to prove efficacy	✓
3	Ensure proper functionality of smoke, flame, and gas sensors	✓
4	Tune machine learning algorithm to detect a fire	✓
5	Test various mechanical designs to determine suitable design enclosure	✓
6	Ensure system behaves as intended	✓
7	Continue maintaining communication between our sections	✓
8	Keep professor and sponsor informed on major updates	✓

**Thank you**

**Questions?**